

Data reduction with POINTLESS and AIMLESS

James Parkhurst

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Purpose

Things we know:

- I , $\text{sig}(I)$, corrected for geometric effects
- Lots of observations
- Symmetry

Things we don't know:

- $|F|^2$
- Beam intensity
- Illuminated volume
- Absorption path through crystal
- Extent of sample decay



This is scaling

Programs

Pointless

- Determines likely point group
- Corrects space group *if* sufficient information
- Sorts reflections
- Detects screw axes & glide planes
- Re-indexes multiple datasets to a common setting

Aimless

- Merges partial reflections together
- Puts data onto a common scale
- Merges each set of symmetry equivalent reflections into a single observation

CTruncate

- Analyses scaled data according to an expected physical model
- Gives statistics on intensity distribution - *e.g.*
 - Wilson statistics
 - twinning analysis
- Outputs $|F|$ values

Symmetry determination (POINTLESS)

Data reduction with POINTLESS and AIMLESS

What does POINTLESS do?

Indexing in eg MOSFLM or DIALS only gives the possible lattice symmetry, ie constraints of unit cell dimensions. Crystal classes: cubic, hexagonal/trigonal, tetragonal, orthorhombic, monoclinic, or triclinic, + lattice centring P, C, I, R, or F

POINTLESS performs the following tasks:

1. from the cell dimensions, determine the maximum possible lattice symmetry (ignoring any input symmetry)
2. for each possible rotation operator, score related observations pairs for agreement (correlation coefficients and R-factor)
3. score all possible combinations of operators to determine the point group (point groups from maximum down to P1)
4. score axial systematic absences to detect screw axes, hence space group (note that axial observations are sometimes unobserved)

Score individual symmetry operators in the maximum lattice group

Analysing rotational symmetry in lattice group P m -3 m

Scores for each symmetry element

Nelmt	Lklhd	Z-cc	CC	N	Rmeas	Symmetry & operator (in Lattice Cell)		
1	0.955	9.70	0.97	13557	0.073	identity		
2	0.062	2.66	0.27	12829	0.488	2-fold	(1 0 1)	{+l, -k, +h}
3	0.065	2.85	0.29	10503	0.474	2-fold	(1 0 -1)	{-l, -k, -h}
4	0.056	0.06	0.01	16391	0.736	2-fold	(0 1 -1)	{-h, -l, -k}
5	0.057	0.05	0.00	17291	0.738	2-fold	(0 1 1)	{-h, +l, +k}
6	0.049	0.55	0.06	13758	0.692	2-fold	(1 -1 0)	{-k, -h, -l}
7	0.950	9.59	0.96	12584	0.100	*** 2-fold k	(0 1 0)	{-h, +k, -l}
8	0.049	0.57	0.06	11912	0.695	2-fold	(1 1 0)	{+k, +h, -l}
9	0.948	9.57	0.96	16928	0.136	*** 2-fold h	(1 0 0)	{+h, -k, -l}
10	0.944	9.50	0.95	12884	0.161	*** 2-fold l	(0 0 1)	{-h, -k, +l}
11	0.054	0.15	0.01	23843	0.812	3-fold	(1 1 1)	{+l, +h, +k} {+k, +l, +h}
12	0.055	0.11	0.01	24859	0.825	3-fold	(1 -1 -1)	{-l, -h, +k} {-k, +l, -h}
13	0.055	0.14	0.01	22467	0.788	3-fold	(1 -1 1)	{+l, -h, -k} {-k, -l, +h}
14	0.055	0.12	0.01	27122	0.817	3-fold	(1 1 -1)	{-l, +h, -k} {+k, -l, -h}
15	0.061	-0.10	-0.01	25905	0.726	4-fold h	(1 0 0)	{+h, -l, +k} {+h, +l, -k}
16	0.060	2.53	0.25	23689	0.449	4-fold k	(0 1 0)	{+l, +k, -h} {-l, +k, +h}
17	0.049	0.56	0.06	25549	0.653	4-fold l	(0 0 1)	{-k, +h, +l} {+k, -h, +l}

Only orthorhombic symmetry operators are present

Score possible point groups

All possible combinations of rotations are scored to determine the point group. Good scores in symmetry operations which are absent in the sub-group count against that group.

Example: C-centred orthorhombic which might be hexagonal

	Laue Group		Lklhd	NetZc	Zc+	Zc-	CC	CC-	Rmeas	R-	Delta	ReindexOperator
= 1	C m m m	***	0.989	9.45	9.62	0.17	0.96	0.02	0.08	0.76	0.0	[h,k,l]
2	P 1 2/m 1		0.004	7.22	9.68	2.46	0.97	0.25	0.06	0.56	0.0	[-1/2h+1/2k, -1, -1/2h-1/2k]
3	C 1 2/m 1		0.003	7.11	9.61	2.50	0.96	0.25	0.08	0.55	0.0	[h,k,l]
4	C 1 2/m 1		0.003	7.11	9.61	2.50	0.96	0.25	0.08	0.55	0.0	[-k, -h, -l]
5	P -1		0.000	6.40	9.67	3.27	0.97	0.33	0.06	0.49	0.0	[1/2h+1/2k, 1/2h-1/2k, -l]
6	C m m m		0.000	1.91	5.11	3.20	0.51	0.32	0.34	0.51	2.5	[1/2h-1/2k, -3/2h-1/2k, -l]
7	P 6/m		0.000	1.16	4.59	3.43	0.46	0.34	0.41	0.46	2.5	[-1/2h-1/2k, -1/2h+1/2k, -l]
8	C 1 2/m 1		0.000	1.51	5.15	3.64	0.52	0.36	0.33	0.47	2.5	[1/2h-1/2k, -3/2h-1/2k, -l]
9	C 1 2/m 1		0.000	1.51	5.15	3.64	0.51	0.36	0.33	0.47	2.5	[-3/2h-1/2k, -1/2h+1/2k, -l]
10	P -3		0.000	1.04	4.75	3.71	0.48	0.37	0.40	0.45	2.5	[-1/2h-1/2k, -1/2h+1/2k, -l]
11	C m m m		0.000	2.13	5.23	3.10	0.52	0.31	0.32	0.52	2.5	[-1/2h-1/2k, -3/2h+1/2k, -l]
12	C 1 2/m 1		0.000	1.64	5.25	3.61	0.53	0.36	0.32	0.47	2.5	[-1/2h-1/2k, -3/2h+1/2k, -l]
13	C 1 2/m 1		0.000	1.67	5.27	3.60	0.53	0.36	0.32	0.47	2.5	[-3/2h+1/2k, 1/2h+1/2k, -l]
14	P -3 1 m		0.000	0.12	4.00	3.87	0.40	0.39	0.44	0.44	2.5	[-1/2h-1/2k, -1/2h+1/2k, -l]
15	P -3 m 1		0.000	0.14	4.00	3.86	0.40	0.39	0.44	0.44	2.5	[-1/2h-1/2k, -1/2h+1/2k, -l]
16	P 6/m m m		0.000	3.93	3.93	0.00	0.39	0.00	0.44	0.00	2.5	[-1/2h-1/2k, -1/2h+1/2k, -l]

Possible spacegroups:

Indistinguishable space groups are grouped together on successive lines

'Reindex' is the operator to convert from the input hklin frame to the standard spacegroup frame.

'TotProb' is a total probability estimate (unnormalised)

'SysAbsProb' is an estimate of the probability of the space group based on the observed systematic absences.

'Conditions' are the reflection conditions (absences)

Spacegroup	TotProb	SysAbsProb	Reindex	Conditions
<P 21 21 21> (19)	0.838	0.851		h00: h=2n, 0k0: k=2n, 00l: l=2n (zones 1,2,3)
<P 2 21 21> (18)	0.104	0.106		0k0: k=2n, 00l: l=2n (zones 2,3)
<P 21 2 21> (18)	0.025	0.026		h00: h=2n, 00l: l=2n (zones 1,3)
<P 21 21 2> (18)	0.012	0.012		h00: h=2n, 0k0: k=2n (zones 1,2)

Best Solution space group P 21 21 21

Reindex operator: [h,k,l]
Laue group probability: 0.985
Systematic absence probability: 0.851
Total probability: 0.838
Space group confidence: 0.784
Laue group confidence: 0.982

Note high confidence in Laue group, but lower confidence in space group

Unit cell: 34.16 54.8 68 90 90 90

17.00 to 1.78 - Resolution range used for Laue group search

17.00 to 1.78 - Resolution range in file, used for systematic absence check

Number of batches in file: 100

What can go wrong?

- Pseudo-symmetry or twinning (often connected) can suggest a point group symmetry which is too high. Careful examination of the scores for individual symmetry operators may indicate the truth (the program is not foolproof!)
- POINTLESS works (usually) with unscaled data (hence use of correlation coefficients), so data with a large range of scales, including a dead crystal, may give a too-low symmetry.
- In bad cases either just use the first part of the data, or scale in P1 and run POINTLESS on the scaled unmerged data
- Potential axial systematic absences may be absent or few, so it may not be possible to determine the space group. In that case the output file is labelled with the “space group” with no screw axes, eg P2, P222, P622 etc, and the space group will have to be determined later

NOTE that the space group is only a hypothesis until the structure has been determined and satisfactorily refined

Scaling (AIMLESS)

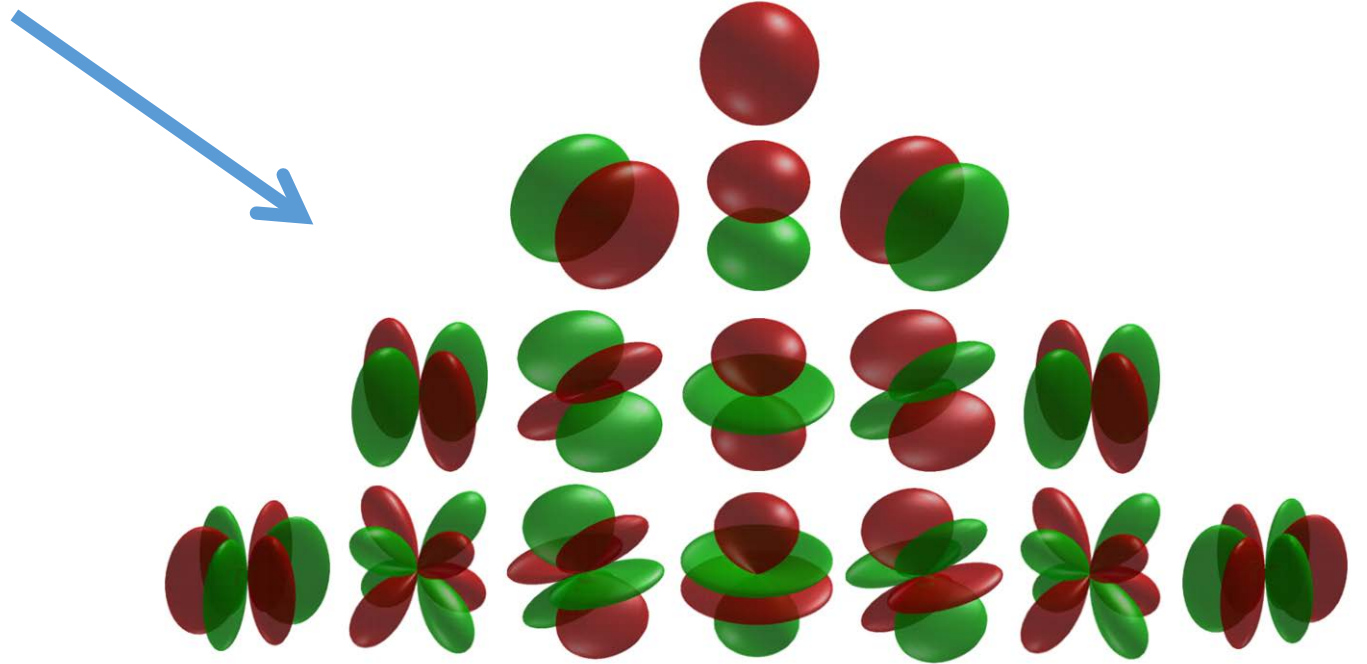
Data reduction with POINTLESS and AIMLESS

Scaling

- Corrections for some of the things we don't know can be determined experimentally
- In most cases however empirical corrections are determined
- Have a model for: overall scale (beam intensity + illuminated volume) sample decay and absorption
- Refine model against data, to minimise differences between symmetry related intensities

Scaling models

- Time or frame # dependent – overall scale
- Time and resolution dependent – decay
- Direction dependent – absorption – for example as spherical harmonics
- All depends on multiplicity



Objective of scaling

- To model all of the unknown contributions to the measured intensity
- To recover $I = k |F|^2$ for each observation
- Achieved by minimizing the differences between observations – internally consistent not necessarily correct!
- Final result of scaling is average $I = k |F|^2$ for each unique Miller index
- May want to keep I^+ and I^- separate

Factors related to incident X-ray beam

- incident beam intensity: variable on synchrotrons and not normally measured. Assumed to be constant during a single image, or at least varying smoothly and slowly (relative to exposure time). If this is not true, the data will be poor
- illuminated volume: changes with φ if beam smaller than crystal
- absorption in primary beam by crystal: indistinguishable from (b)
- variations in rotation speed and shutter synchronisation. These errors are disastrous, difficult to detect, and (almost) impossible to correct for: we assume that the crystal rotation rate is constant and that adjacent images exactly abut in φ . (*Shutter synchronisation errors lead to partial bias which may be positive, unlike the usual negative bias*)
- Data collection with open shutter (eg with Pilatus detector) avoids synchronisation errors (though variation in rotation speed could still cause trouble, and there is a dead time during readout)

Factors related to crystal and diffracted beam

- Absorption in secondary beam - serious at long wavelength (including $\text{CuK}\alpha$)
- radiation damage - serious on high brilliance sources. Not easily correctable unless small as the structure is changing
- *Maybe extrapolate back to zero time? (but this needs high multiplicity)*
- *The relative B-factor is largely a correction for the average radiation damage*

Factors related to the detector

- The detector should be properly calibrated for spatial distortion and sensitivity of response, and should be stable. Problems with this are difficult to detect from diffraction data. There are known problems in the tile corners of CCD detectors (corrected for in XDS)
- The useful area of the detector should be calibrated or told to the integration program
 - Calibration should flag defective pixels (hot or cold) and dead regions eg between tiles
 - The user should tell the integration program about shadows from the beamstop, beamstop support or cryo-cooler (define bad areas by circles, rectangles, arcs etc)

Data Quality

Data reduction with POINTLESS and AIMLESS

Judging data quality

- Are there bad batches?
- Was the radiation damage such that you should exclude the later parts?
- Is the outlier detection working well?
- What is the real resolution? Should you cut the high-resolution data?
- Is there any apparent anomalous signal?
- What is the overall quality of the dataset?
- Are the data twinned?

AIMLESS summary statistics

	Overall	InnerShell	OuterShell
Low resolution limit	150.01	150.01	1.19
High resolution limit	1.17	6.41	1.17
Rmerge (within I+/I-)	0.063	0.024	0.000
Rmerge (all I+ and I-)	0.071	0.027	0.149
Rmeas (within I+/I-)	0.077	0.029	0.000
Rmeas (all I+ & I-)	0.079	0.030	0.210
Rpim (within I+/I-)	0.044	0.016	0.000
Rpim (all I+ & I-)	0.034	0.013	0.149
Rmerge in top intensity bin	0.030	-	-
Total number of observations	324157	3150	300
Total number unique	71073	662	286
Mean((I)/sd(I))	10.8	36.6	2.1
Mn(I) half-set correlation CC(1/2)	0.999	0.999	0.775
Completeness	82.0	99.9	6.9
Multiplicity	4.6	4.8	1.0
Anomalous completeness	71.3	100.0	0.4
Anomalous multiplicity	2.2	3.1	1.0
DelAnom correlation between half-sets	0.004	0.149	0.000
Mid-Slope of Anom Normal Probability	0.997	-	-

R-factors

$$R_{merge} = \frac{\sum_{hkl} \sum_j |I_{hkl,j} - \langle I_{hkl} \rangle|}{\sum_{hkl} \sum_j I_{hkl,j}}$$

$$R_{meas} = \frac{\sum_{hkl} \sqrt{\frac{n}{n-1}} \sum_{j=1}^N |I_{hkl,j} - \langle I_{hkl} \rangle|}{\sum_{hkl} \sum_j I_{hkl,j}}$$

$$R_{pim} = \frac{\sum_{hkl} \sqrt{\frac{1}{n-1}} \sum_{j=1}^N |I_{hkl,j} - \langle I_{hkl} \rangle|}{\sum_{hkl} \sum_j I_{hkl,j}}$$

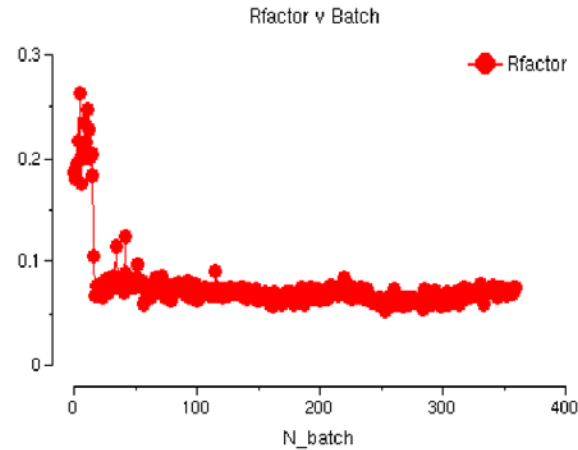
The traditional overall measures of quality, but increases with multiplicity although the data improves

Multiplicity-weighted, better (but larger)

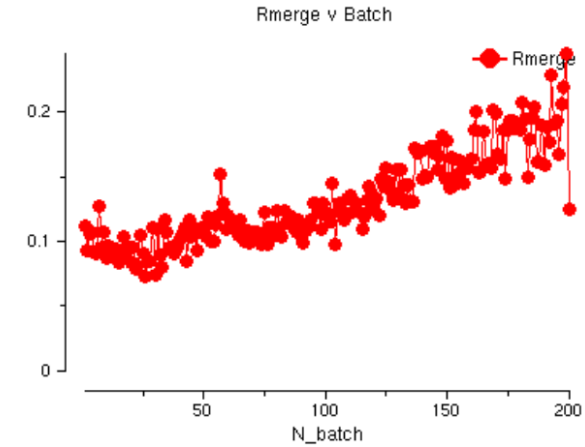
“Precision-indicating R-factor” gets better (smaller) with increasing multiplicity, ie it estimates the precision of the merged $\langle I \rangle$

Rmerge: finding bad batches

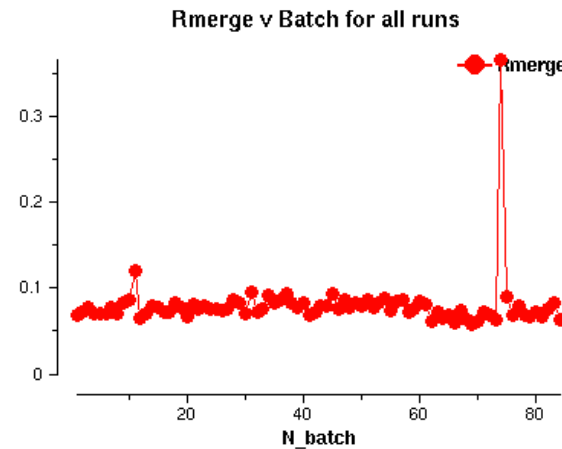
Horribly wrong at beginning



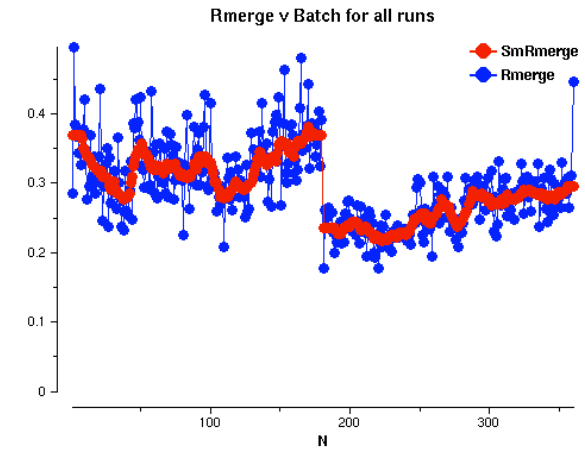
Steady decline in quality



One bad batch



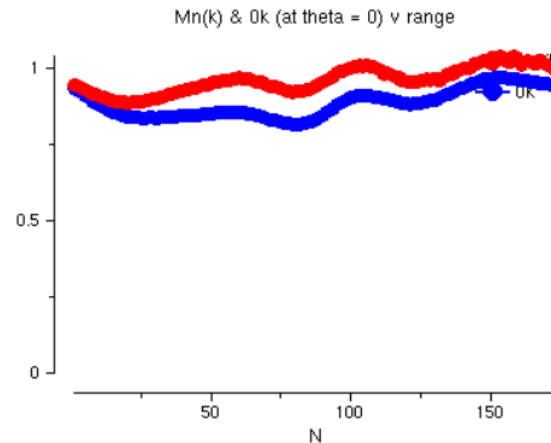
Batches for 2 crystals



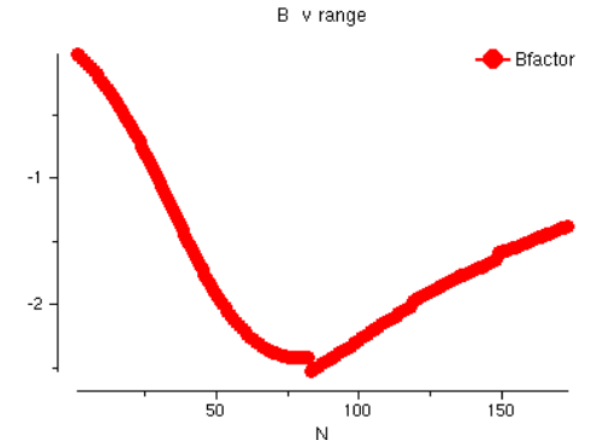
Would like to have relatively stable Rmerge across all batches

Scales and B-factors: radiation damage

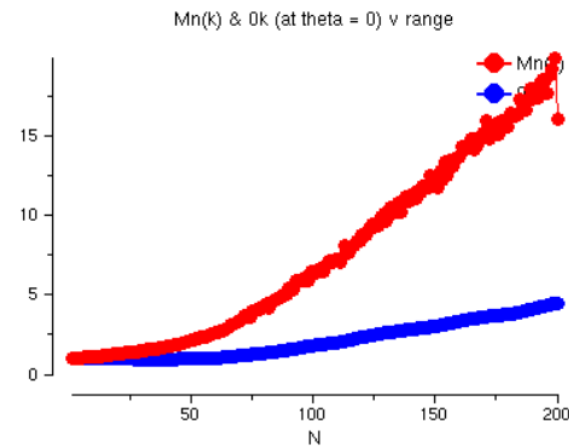
Good: scales uniform



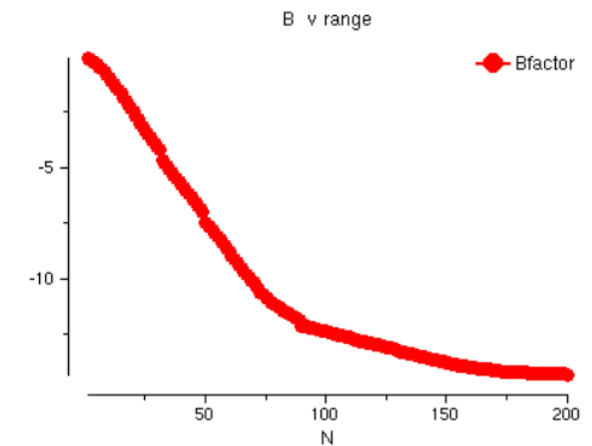
Good: small B-factors



Bad: scales increase sharply



Bad: B-factors large and negative

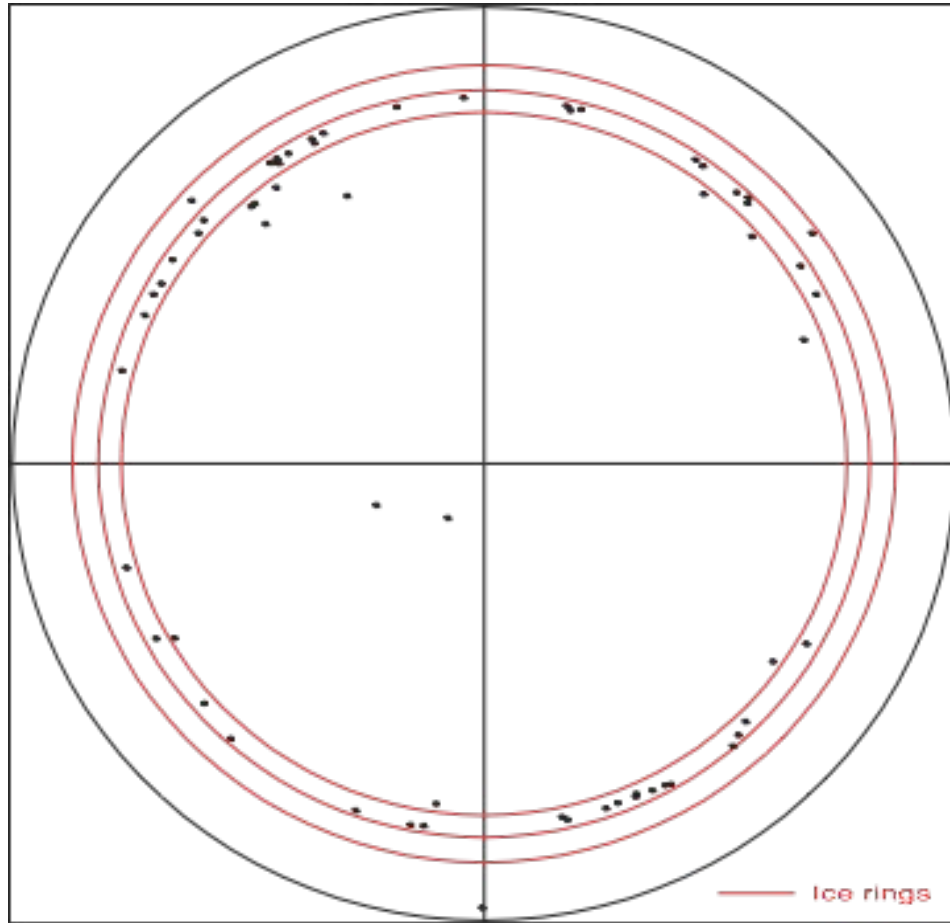


Ideally have constant scaling factor of 1; except if crystals have an irregular shape. Drop in B factor below -10 indicates radiation damage

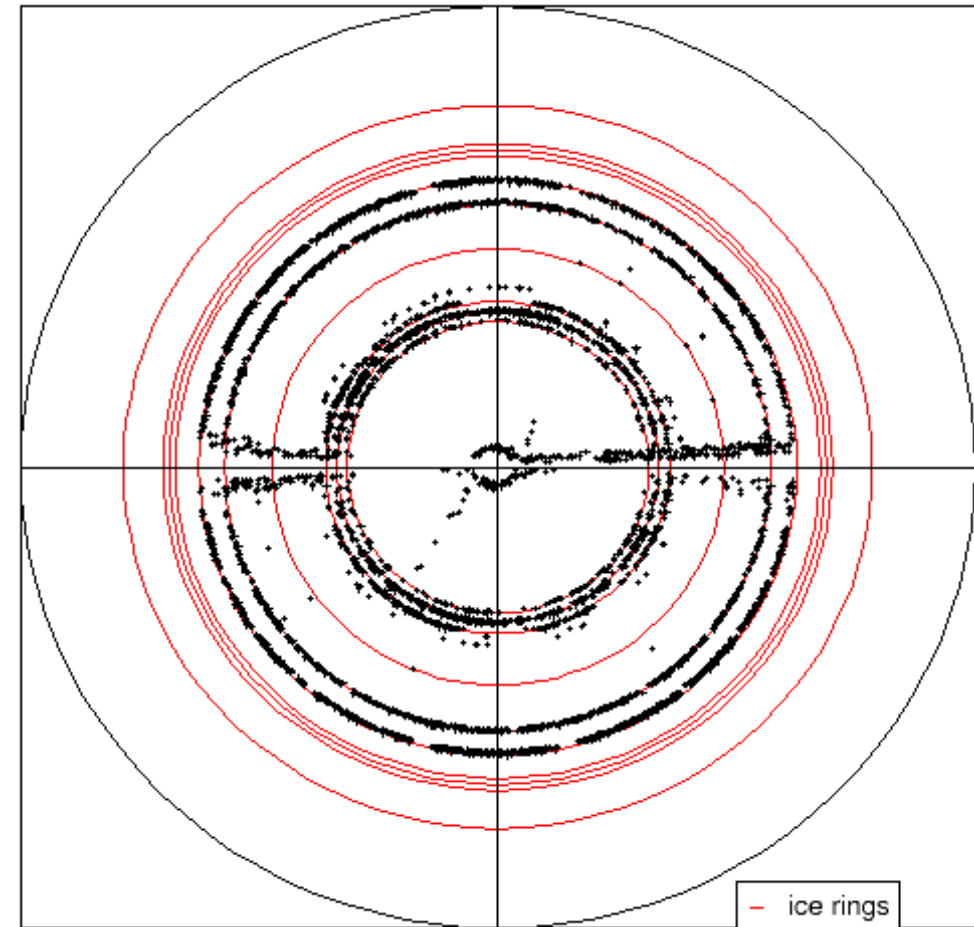
Outliers: why do we get them?

- outside reliable area of detector (eg behind shadow)
 - specify backstop shadow, calibrate detector
- ice spots
 - do not get ice on your crystal!
- multiple lattices
 - find single crystal
- zingers
- bad prediction (spot not there)
 - improve prediction
- spot overlap
 - lower mosaicity, collect finer sliced data, move detector back, deconvolute overlaps

Outliers: ROGUEPLOT



A few outliers on ice rings



Lots of reflections on ice rings

Outliers: number of rejections per image

N	Run.Rot	MidPhi	Batch	Bfactor	Mn(k)	σ_k	Number	NumReject
1	1.1	-49.50	1	-0.694	1.0651	0.9940	1703	0
2	1.2	-48.50	2	-0.688	1.0622	0.9905	2193	0
3	1.3	-47.50	3	-0.677	1.0564	0.9851	2219	0
4	1.4	-46.50	4	-0.668	1.0453	0.9774	2202	0
5	1.5	-45.50	5	-0.656	1.0339	0.9671	2198	0
6	1.6	-44.50	6	-0.641	1.0180	0.9542	2217	1
7	1.7	-43.50	7	-0.629	1.0017	0.9395	2208	0
8	1.8	-42.50	8	-0.614	0.9811	0.9185	2217	0

Want low number of rejected reflections per image; a maximum of around 5

Resolution

What do we mean by the “resolution” of the data?

We want to determine the point at which adding another shell of data does not add any “significant” information.

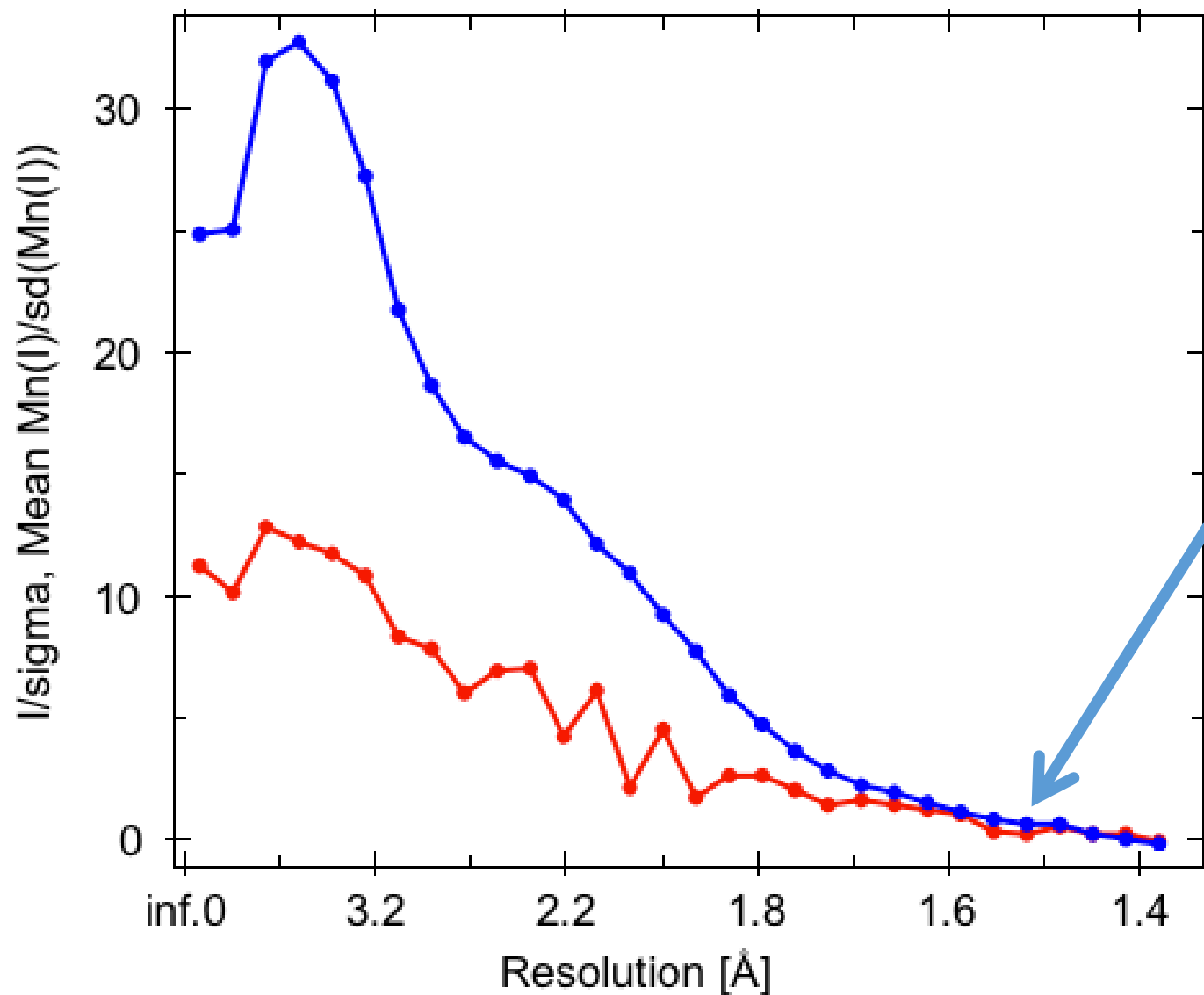
Resolution

“Best” resolution is different for different purposes, so don’t cut it too soon

- Experimental phasing: substructure location is generally unweighted, so cut back conservatively to data with high signal/noise ratio. For phasing, use all “reasonable” data
- Molecular replacement: Phaser uses likelihood weighting, but there is probably no gain in using the very weak high resolution data
- Model building and refinement: if everything is perfectly weighted (perfect error models!), then extending the data should do no harm and may do good

There is no reason to suppose that cutting back the resolution to satisfy referees will improve your model!

Resolution: $I/\sigma(I)$



$I/\sigma(I)$ around 1.5

A reasonably good criterion, but it relies on $\sigma(I)$, which is not entirely reliable

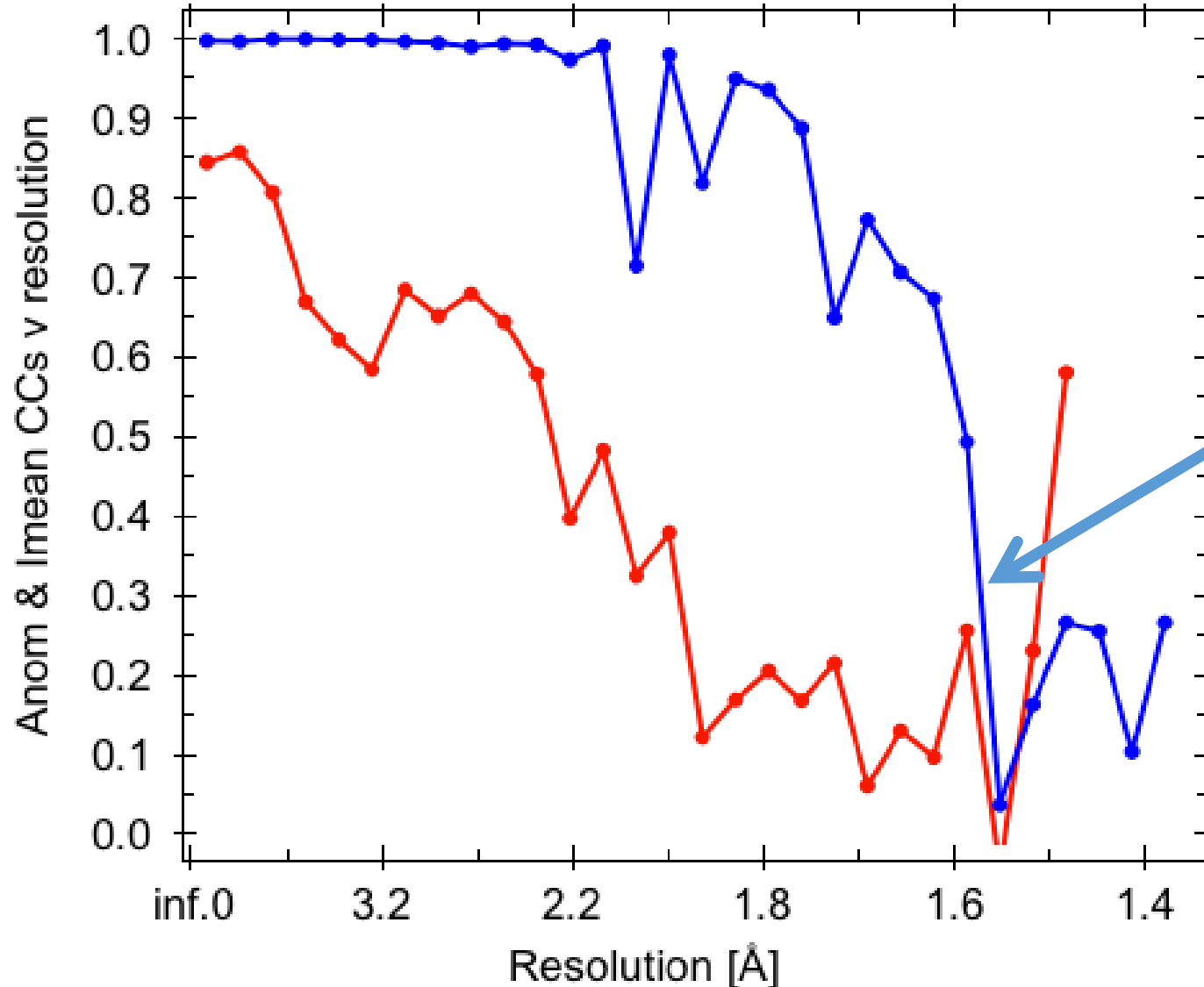
CC ½ around 0.3

Split observations for each reflection randomly into 2 halves, and calculate the correlation coefficient between them

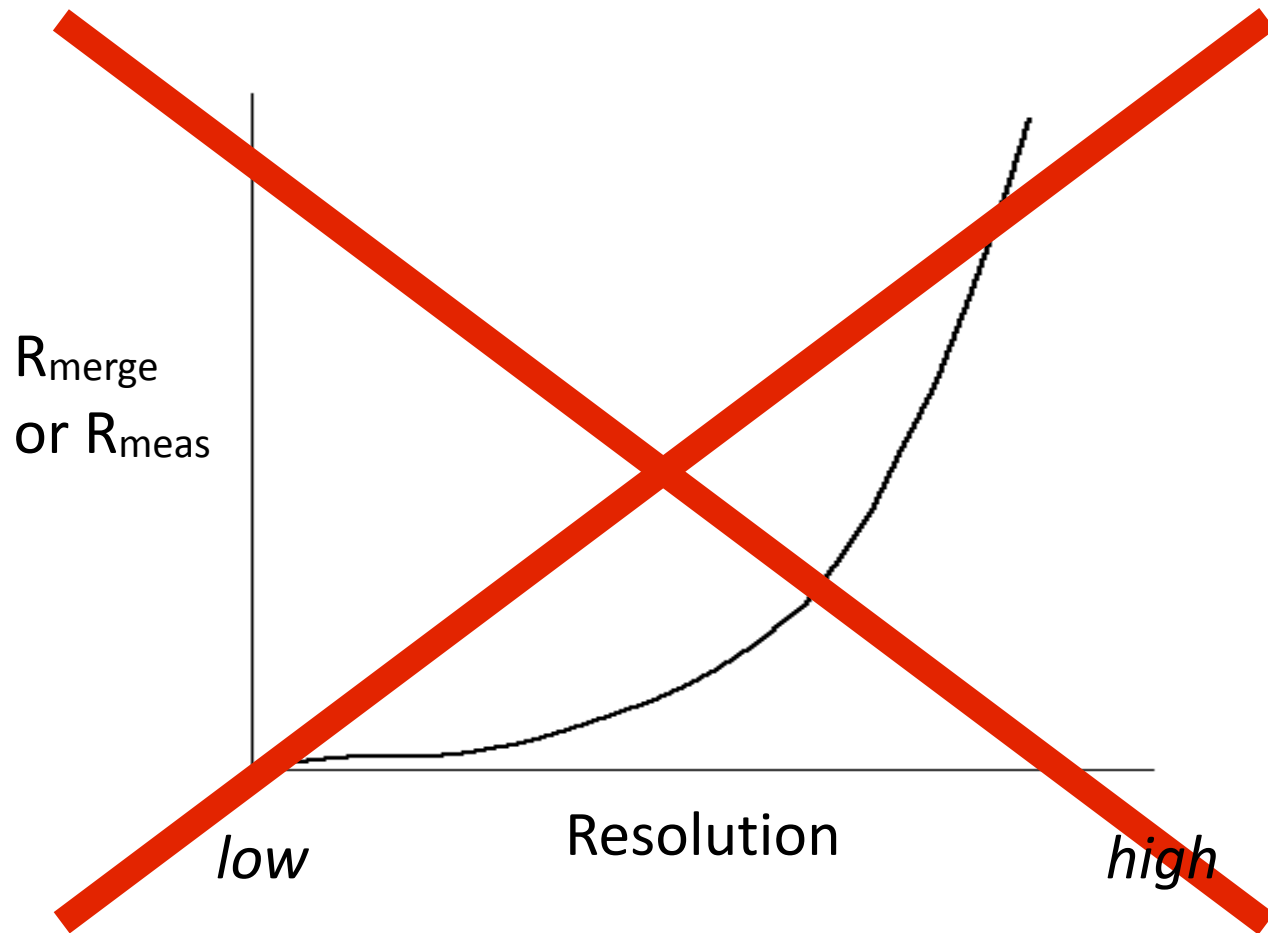
Advantages:

- Clear meaning to values (1.0 is perfect, 0 is no correlation), known statistical properties
- Independent of $\sigma(I)$

Resolution: CC 1/2



Resolution: $R_{\text{merge}}/R_{\text{meas}}$

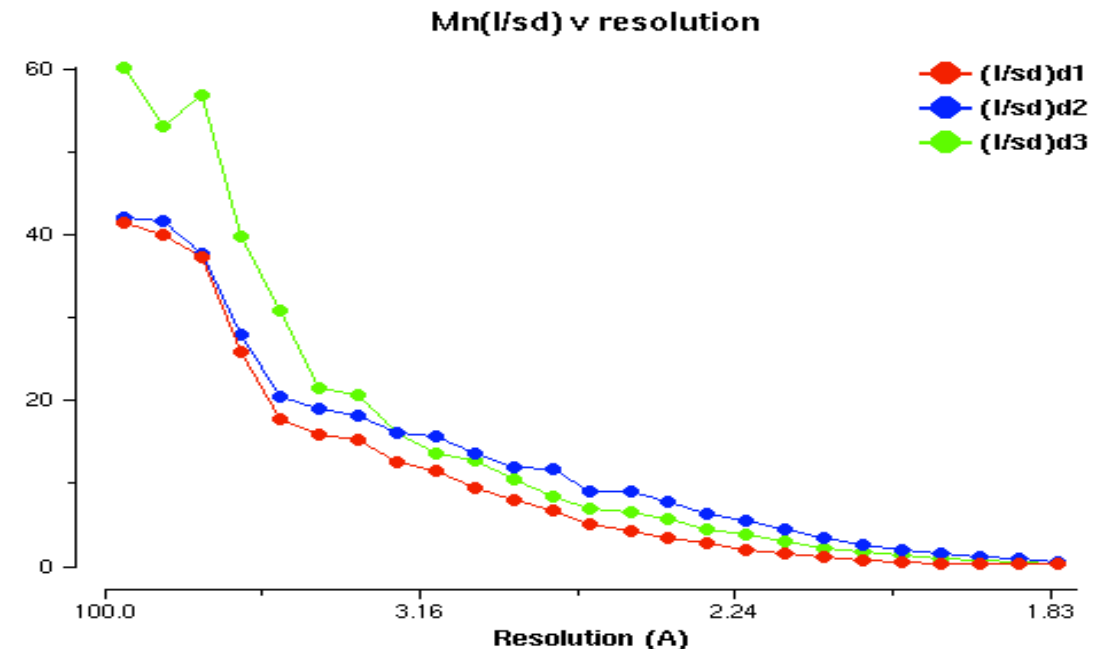
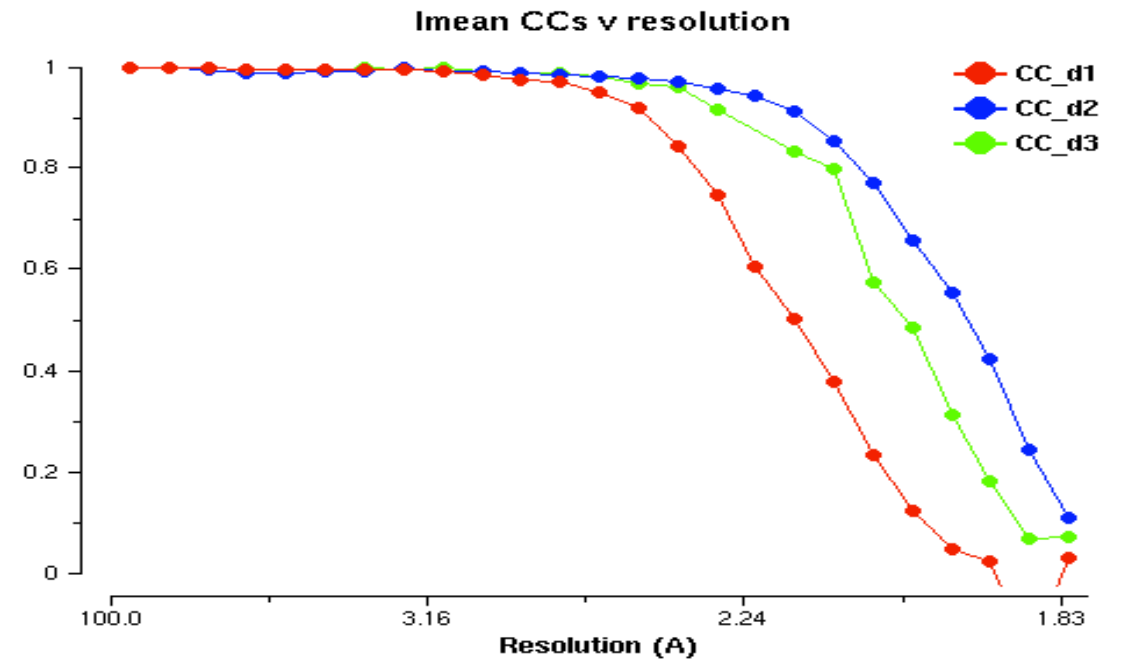


Note that R_{merge} and R_{meas} are useful for other purposes, but not for deciding the resolution cutoff

Note that the crystallographic R-factor behaves quite differently: at higher resolution as the data become noisier, R_{cryst} tends to a constant value, not to infinity

Resolution: anisotropy

- Many (perhaps most) datasets are *anisotropic*
- The principal directions of anisotropy are defined by symmetry (axes or planes), except in the monoclinic and triclinic systems, in which we can calculate the orthogonal principle directions
- We can then analyse half-dataset CCs or $\langle I/\sigma(I) \rangle$ in cones around the principle axes, or as projections on to the axes
- Anisotropic cutoffs are probably a Bad Thing, since it leads to strange series termination errors and problem with intensity statistics



Resolution: aimless log file

Estimates of resolution limits: overall

from half-dataset correlation $CC(1/2) > 0.30$: limit = 3.15A
from $Mn(I/sd) > 1.50$: limit = 3.17A
from $Mn(I/sd) > 2.00$: limit = 3.30A

Estimates of resolution limits in reciprocal lattice directions:

Along h k plane

from half-dataset correlation $CC(1/2) > 0.30$: limit = 3.42A
from $Mn(I/sd) > 1.50$: limit = 3.31A

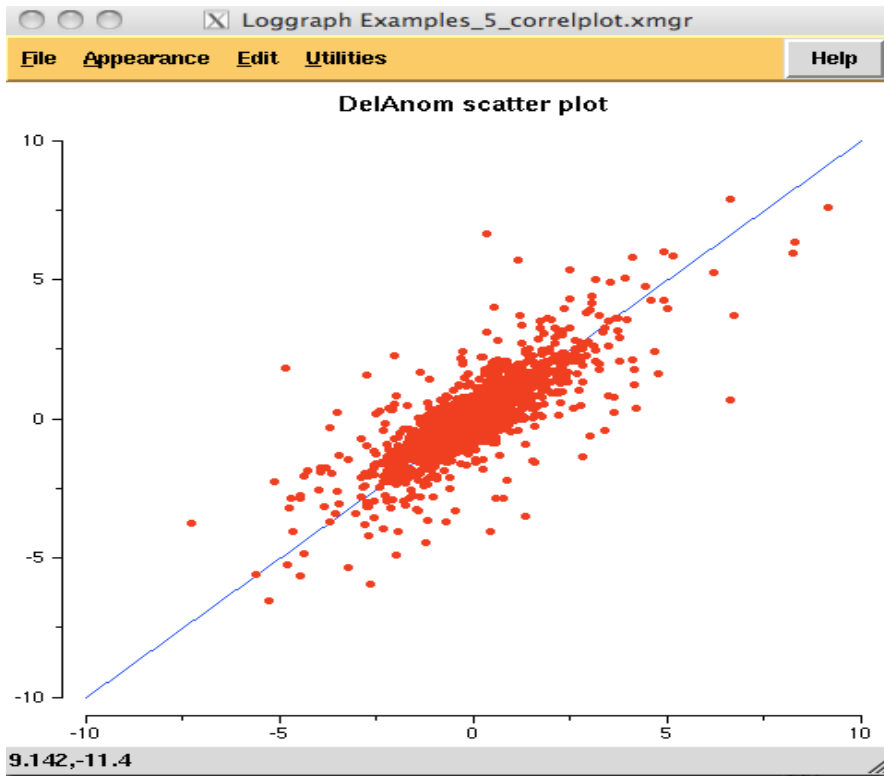
Along l axis

from half-dataset correlation $CC(1/2) > 0.30$: limit = 3.00A == maximum resolution
from $Mn(I/sd) > 1.50$: limit = 3.00A == maximum resolution

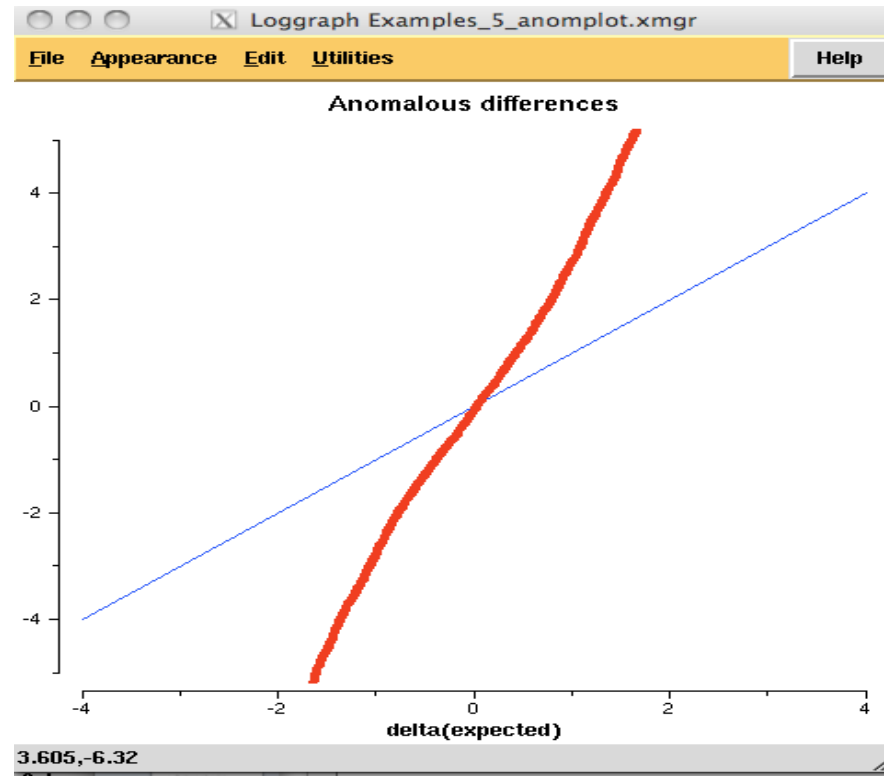
Anomalous signal

- The data contains both I^+ (hkl) and I^- ($-h-k-l$) observations and we can detect whether there is a significant difference between them.
 - Split one dataset randomly into two halves, calculate correlation between the two halves or
 - compare different wavelengths (MAD)

Anomalous signal: strong

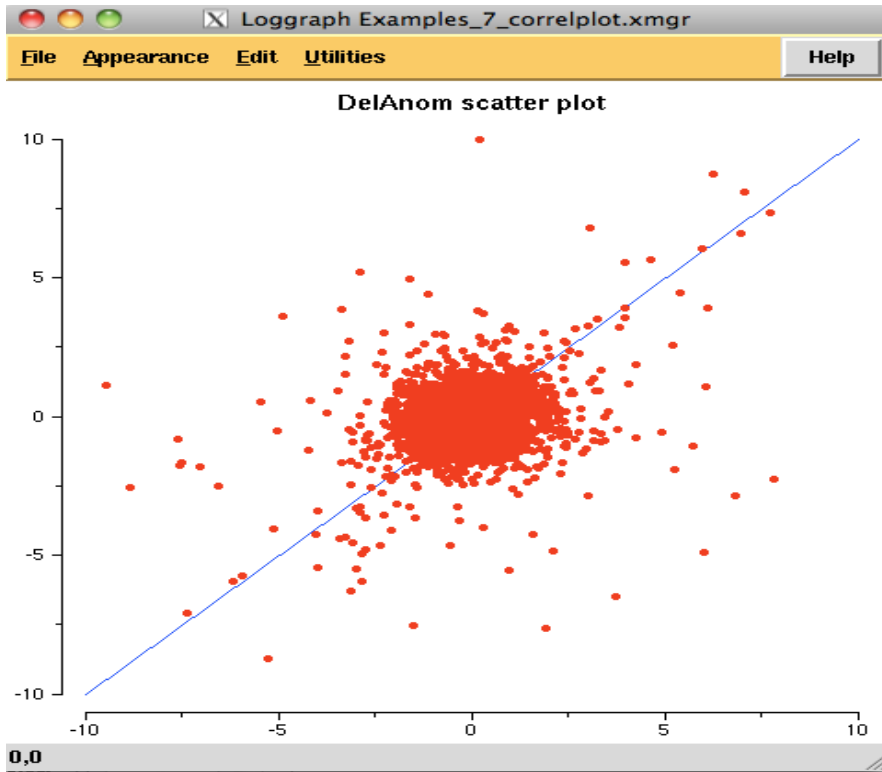


Plot ΔI_1 against ΔI_2 should be elongated along diagonal

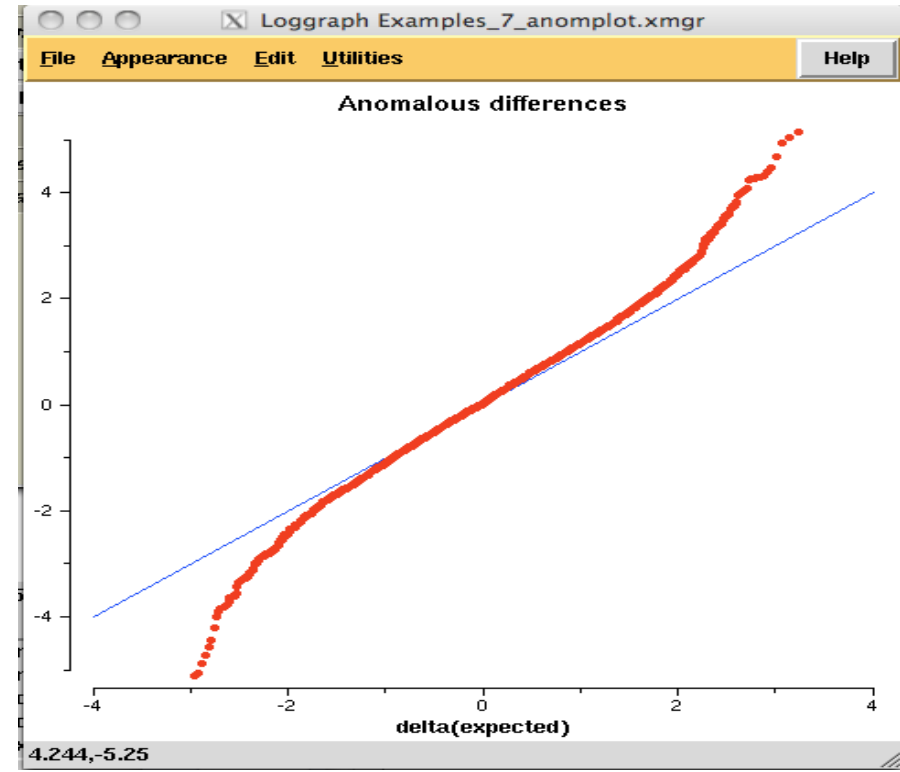


Slope > 1.0 means that $\Delta I > \sigma$

Anomalous signal: weak but useful

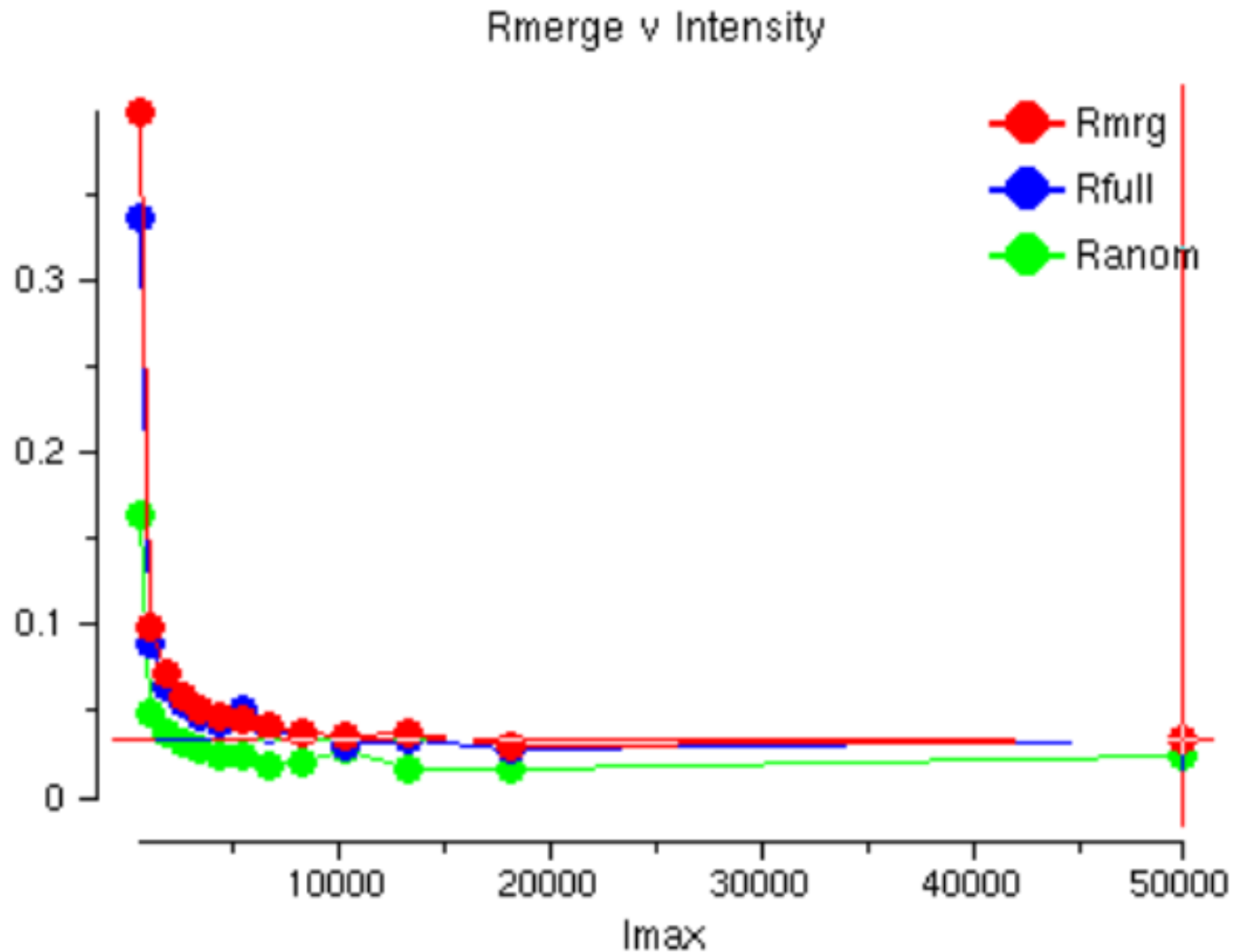


Plot ΔI_1 against ΔI_2 should be elongated along diagonal



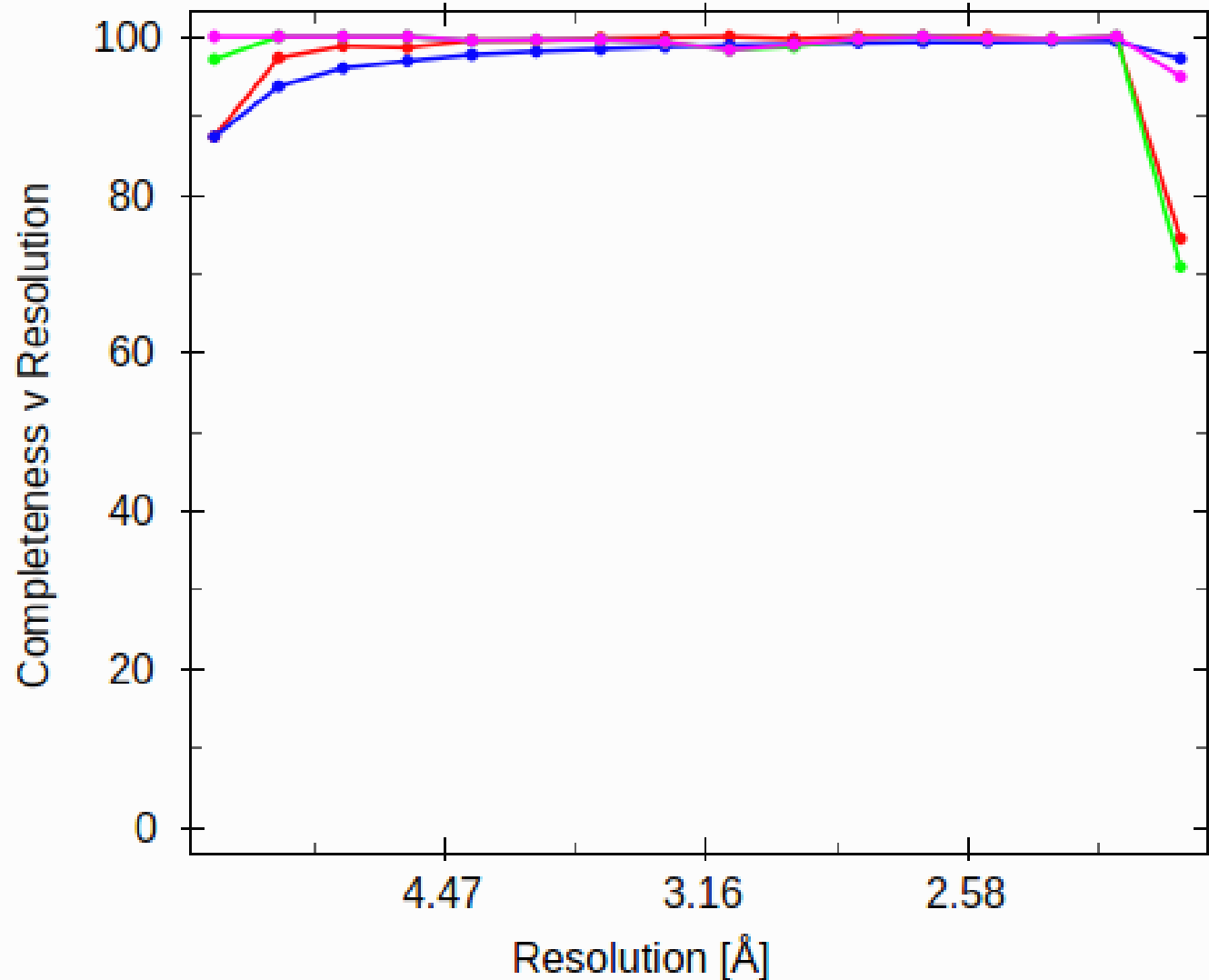
Slope > 1.0 means that $\Delta I > \sigma$

Data Quality: Rmerge vs intensity



Rmerge is always large for small intensities. For large intensities it should be in the range 0.01 to 0.04 for good data. Larger values suggest that there are systematic errors.

Data Quality: completeness



Completeness of data should be as close to 100% as possible.

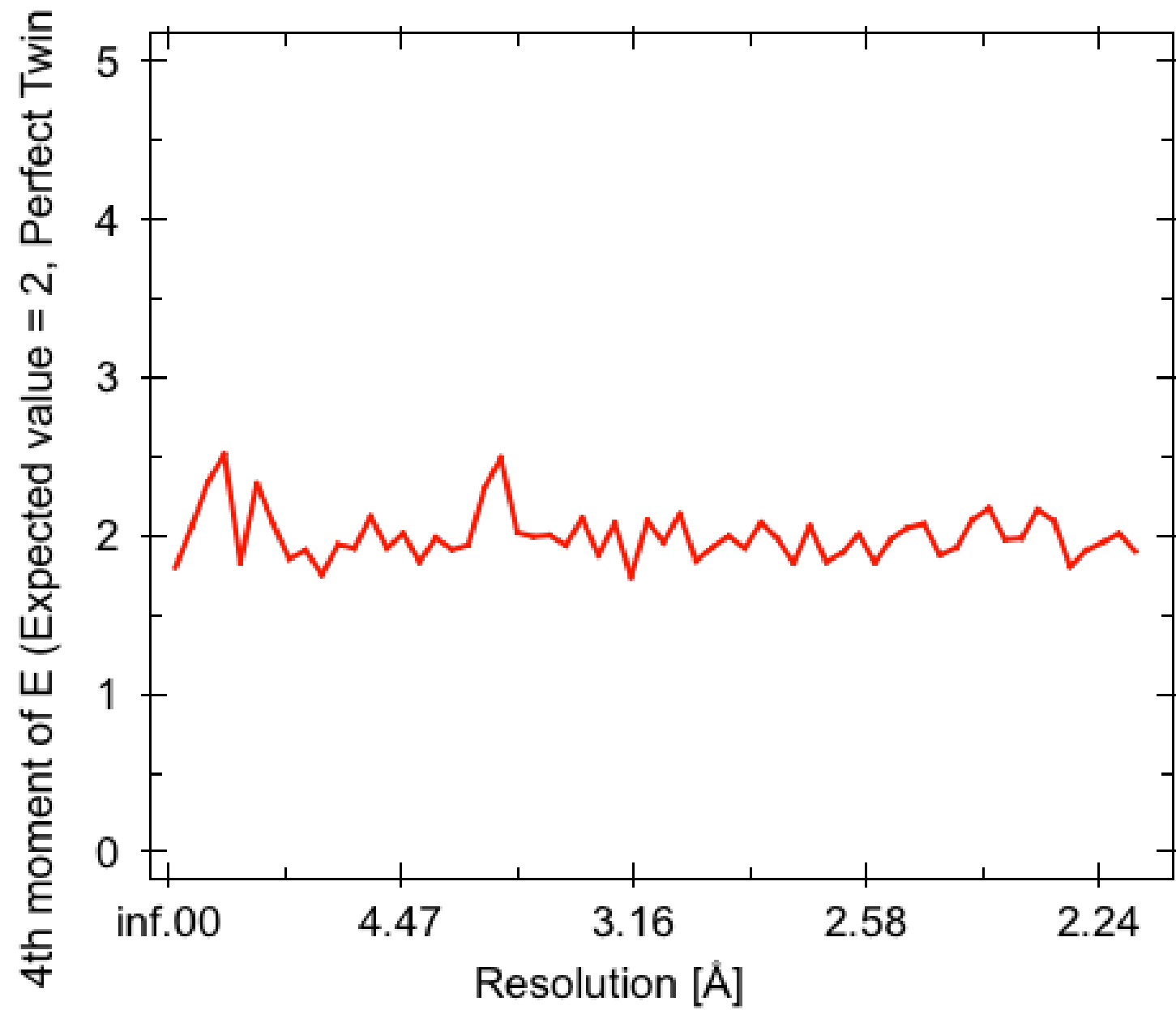
Watch out for data with < 95% completeness.

Some loss of completeness can be tolerated in the outermost resolution bins.

If you integrate to the corners of the detector, you may have low completeness at high resolution.

Detecting twinning

- Depends on moments of intensity distributions
- Acentric E^4 is useful: if 2 probably not twinned, if 1.5 probably twinned
- Measures the spread of the merged intensity distribution
- Look at ctruncate output
- More twinning tests are performed, check ctruncate log



Things that might look like twinning but are not

Translational non-crystallographic symmetry:

- A whole classes of reflections may be weak eg h odd with a NCS translation of $\sim 1/2, 0 0$. $\langle I \rangle$ over all reflections is misleading, so Z values are inappropriate. The reflection classes should be separated (not yet done)

Anisotropy: $\langle I \rangle$ is misleading so Z values are wrong

- ctruncate applies an anisotropic scaling before analysis

Weak data: the ideal statistics are based on perfect data.

- If the signal/noise ratio is small, then the statistics may falsely suggest twinning

Systematic over-estimation of reflection intensities

- With overlapping spots, strong reflections can inflate the value of weak neighbours, leading to too few weak reflections
- Bad outlier rejection for background determination. If background is systematically underestimated, reflections are systematically overestimated (mostly occurs in very weak data).

Data reduction using CCP4 12

Data reduction with POINTLESS and AIMLESS

- Import merged data, sequences, alignments or coordinates
- Integrate X-ray images
- X-ray data reduction and analysis
 - Data reduction - AIMLESS**
Scale and analyse unmerged data and suggest space group (Pointless, Aimless, Ctruncate, FreeRflag)
 - Generate a Free R set
Generate a Free R set for a complete set of reflection indices to a given resolution (FreeRflag)
 - Estimate cell content
Estimate number of molecules in the asymmetric unit and solvent content (Matthews_coeff)
 - Calculate self rotation function
Evaluate data for anisotropy, optical resolution, pseudo translation and perform self-rotation function
- Experimental phasing
- Bioinformatics and model preparation for Molecular Replacement
- Molecular Replacement
- Model building and Graphics
- Refinement
- Ligands
- Validation and analysis
- Export and Deposition
- Reflection data tools
- Coordinate data tools
- Developer tools

New job

Cancel

Click the aimless data reduction job item.




Click "new job" to open the aimless job window.

Job 1: Data reduction - AIMLESS **The job is Pending**

Input Results Comments

Input Data Important Options Additional Options


Job title Data reduction

 Use data from job No as input below.. Show list Select unmerged data files Unmerged reflections loaded from 6_integrated.mtz by job 1

Crystal name FROMDIALS

dataset name FROMDIALS

Batches in file: 2 - 541

Exclude batches from calculations and output Resolution range (Å) to Maximum resolution in files 1.17Å use explicit resolution range in symmetry determination as well as in scalingOptions for symmetry determination Determine Laue group and space group **Optional input data****1. Reference data to resolve indexing ambiguity and space group** use reference data in analysis against Batch after scalingReference data are Reflection list and is optionally defined in next line Reflections ..is not used **2. Optional existing FreeR set, define to copy or extend if necessary** Free R set ..is not used

Select an MTZ file containing integrated reflections from MOSFLM, DIALS or XDS etc

Job 1: Data reduction - AIMLESS *The job is Pending*

Input Results Comments

Input Data Important Options Additional Options

Job title Data reduction

Use data from job No as input below..

Show list Select unmerged data files

Unmerged reflections loaded from 6_integrated.mtz by job 1

Crystal name FROMDIALS

dataset name FROMDIALS

Batches in file: 2 - 541

Exclude batches from calculations and output 400-541

Resolution range (Å) 40.0 to 2.0 Maximum resolution in files 2.153

 use explicit resolution range in symmetry determination as well as in scaling

Options for symmetry determination Determine Laue group and space group

Optional input data**1. Reference data to resolve indexing ambiguity and space group** use reference data in analysis against Batch after scaling

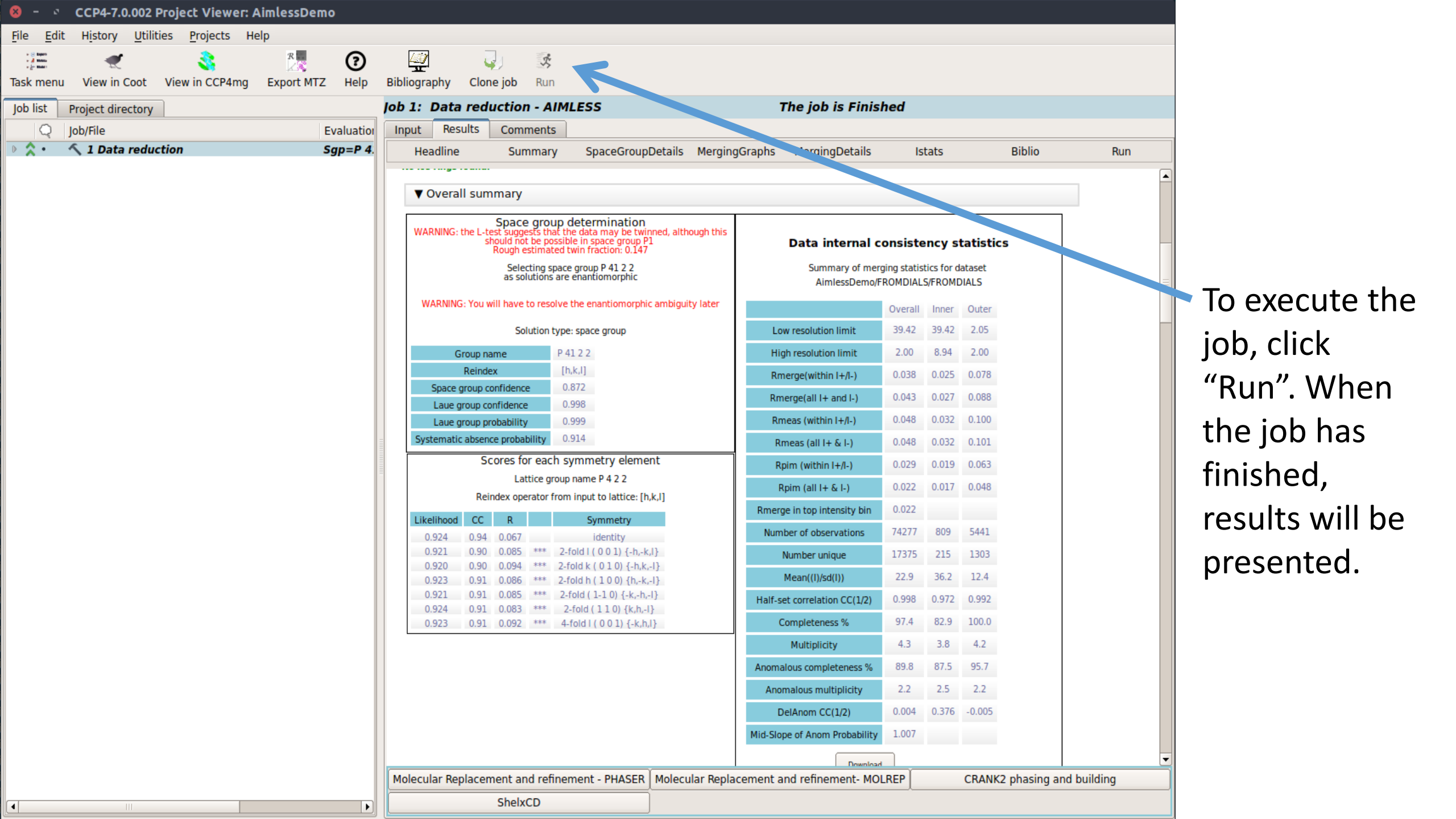
Reference data are Reflection list and is optionally defined in next line

Reflections ..is not used

2. Optional existing FreeR set, define to copy or extend if necessary

Free R set ..is not used

If necessary, exclude batches or set a resolution range for scaling.



Job/File Evaluation

- • • 3 Data reduction
- • • 2 Data reduction
- • • 1 Data reduction

Sgp=P 4.

Input Results Comments

Input Data Important Options Additional Options

job title Data reduction

Use data from job No as input below..

Show list Select unmerged data files

1 Unmerged reflections loaded from 6_integrated.mtz by job 1

Crystal name FROMDIALS dataset name FROMDIALS

Batches in file: 2 - 541

Exclude batches from calculations and output 400-541

Resolution range (Å) 40.0 to 2.0 Maximum resolution in files 1.17Å

use explicit resolution range in symmetry determination as well as in scaling

Options for symmetry determination Match index to reference data

Optional input data

1. Reference data to resolve indexing ambiguity and space group

use reference data in analysis against Batch after scaling

Reference data are Reflection list and MUST be defined in next line

Reflections Reflections loaded from reference.mtz by job 3

2. Optional existing FreeR set, define to copy or extend if necessary

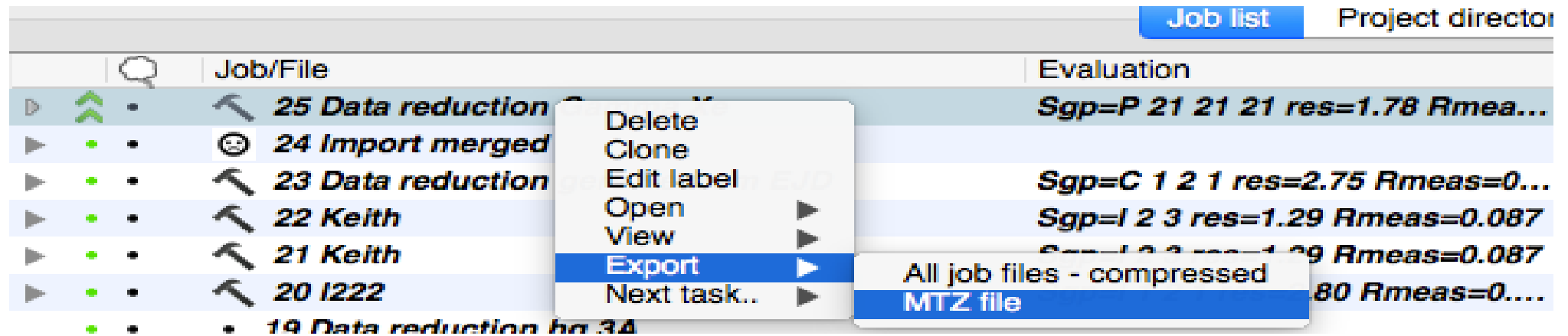
Free R set ..is not used



To select a reference MTZ file to resolve indexing ambiguity, select "Reflection list" and specify the reference reflection file.

Exporting from I2

Right-click the finished job in the Job list and choose Export -> MTZ file



Using the command line

```
$ pointless < pointless.dat | tee pointless.log
```

```
--- contents of pointless.dat ---
```

```
HKLIN integrated.mtz
```

```
HKLOUT unscaled.mtz
```

```
HKLREF reference.mtz          # optional
```

```
$ aimless < aimless.dat | tee aimless.log
```

```
--- contents of aimless.dat ---
```

```
HKLIN unscaled.mtz
```

```
HKLOUT scaled.mtz
```

```
RESOLUTION HIGH 2.0          # optional
```

```
EXCLUDE BATCH 450 TO 500    # optional
```

Summary

- *Do look critically at the data processing statistics*
- What is the point group (Laue group)?
- What is the space group?
- Was the crystal dead at the end?
- Is the dataset complete?
- Do you want to cut back the resolution?
- Is this the best dataset so far for this project?
- Should you merge data from multiple crystals?
- Is there anomalous signal (if you expect one)?
- Are the data twinned?

**Try alternative processing strategies: different choices of cutoffs, merging crystals, etc.
Data processing is not necessarily something you just do once.**

Thank you for listening!

<http://www.ccp4.ac.uk>